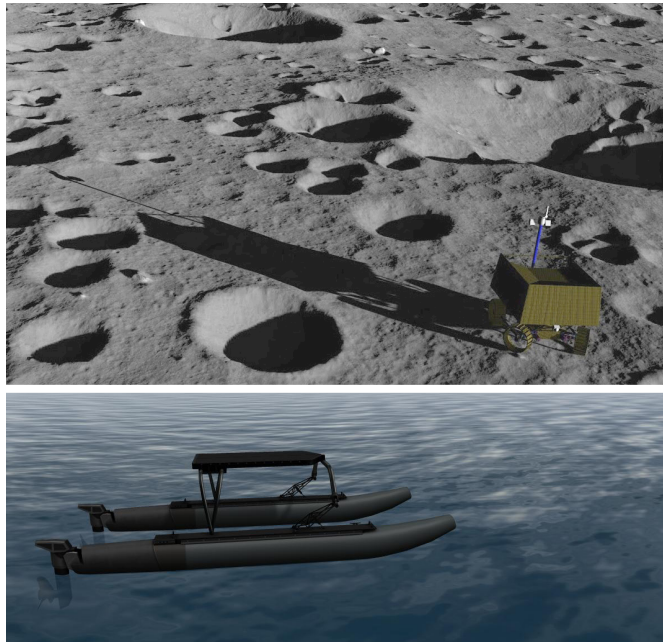


Air, land, sea, and space: Open source robot tools for all

Brian Gerkey

Open Robotics

Mountain View, California



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Developing and deploying robots is hard, and harder still when the robots are sent to far-off places where they cannot be easily helped or serviced. Open Robotics aims to ease that difficulty through the use of high-quality open-source software for robot programming, simulation, and testing. In this seminar, Brian Gerkey will introduce two widely used open source tools—ROS (Robot Operating System) and Gazebo—and show how they have been applied to a wide variety of challenging robot applications, both on Earth and elsewhere.



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